

Technical Data and Specifications

Ratings

M-Max Basic Controller IP20 Standard Ratings

Description	Specification
Protections	
Overcurrent protection	Trip limit $4.0 \times I_{H1}$ instantaneously
Oversvoltage protection	115/230V series: 437 Vdc; 400V series: 874 Vdc; 575V series: 1048 Vdc trip level
Undervoltage protection	115/230V series: 183 Vdc; 400V series: 333 Vdc; 575V series: 460 Vdc trip level
Ground fault protection	Ground fault is tested before every start. In case of ground fault in motor or motor cable, only the frequency converter is protected
Overtemperature protection	Yes
Motor overload protection	Yes
Motor stall protection	Yes
Motor underload protection	Yes

Programmable Parameters

Description
Application macros: basic, pump, fan and high load (hoist)
Programmable start/stop and reverse signal logic (sinking or sourcing)
Reference scaling
Programmable start and stop functions
DC-brake at start and stop
Programmable V/Hz curve
Adjustable switching frequency
Autorestart function after fault
Protections and supervisions (all fully programmable; off, warning, fault)
Current signal input fault
External fault
Fieldbus communication
Eight preset speeds
Analog input range selection, signal scaling and filtering
PID controller
Skip frequencies

Specifications

M-Max Series Drives

Description	Specification
Input Ratings	
Input voltage (V_{in})	+10%/–15% (575V units: +15%/–15%)
Input frequency (f_{in})	50/60 Hz (variation up to 45–66 Hz)
Connection to power	Once per minute or less (typical operation)
Output Ratings	
Output voltage	0 to V_{in} ①
Continuous output current	Continuous rated current I_N at ambient temperature max. 122°F (50°C), overload $1.5 \times I_N$ max. 1 min/10 min
Output frequency	0 to 320 Hz
Frequency resolution	0.01 Hz
Initial output current (I_{H1})	Current $2 \times I_N$ for 2 seconds in every 20-second period Torque depends on motor
Control Characteristics	
Control method	Frequency control (V/Hz) open loop or sensorless vector control
Switching frequency	1.5 to 16 kHz; default 6 kHz
Frequency reference	Analog input: resolution 0.1% (10-bit), accuracy $\pm 1\%$ V/Hz Panel reference: resolution 0.01 Hz
Field weakening point	30 to 320 Hz
Acceleration time	0 to 3000 sec
Deceleration time	0 to 3000 sec
Braking torque	DC brake: $30\% \times T_n$ (without brake option)
Brake Resistor (Minimum Values) ②	
230V Series	FS2 35 ohms and FS3 26 ohms
400V Series	FS2 75 ohms and FS3 54 ohms
575V Series	FS3 103 ohms
Ambient Conditions	
Ambient operating temperature	14°F (–10°C), no frost to 122°F (+50°C): Rated loadability I_N
Storage temperature	–40°F (–40°C) to 158°F (70°C)
Relative humidity	0 to 95% RH, noncondensing, non-corrosive, no dripping water
Air quality	Chemical vapors: IEC 721-3-3, unit in operation, Class 3C2; Mechanical particles: IEC 721-3-3, unit in operation, Class 3S2
Altitude	100% load capacity (no derating) up to 3280 ft (1000m); 1% derating for each 328 ft (100m) above 3280 ft (1000m); max. 6560 ft (2000m)
Vibration	EN 60068-2-6; 3 to 150 Hz, displacement amplitude 1 mm (peak) at 3 to 15.8 Hz, max. acceleration amplitude 1G at 15.8 to 150 Hz
Shock	EN 50178, IEC 68-2-27 UPS Drop test (for applicable UPS weights); storage and shipping: max. 15G, 11 ms (in package)
Enclosure class	IP20

Notes

① Exception: 115V single-phase in, 230V three-phase out.

② Only three-phase FS2 and FS3 drives are equipped with brake chopper circuit.

Standards

2

I/O Specifications

- Digital inputs DI1–DI6 are freely programmable. The user can assign multiple functions to a single input
- Digital, relay, and analog outputs are freely programmable

Includes:

- Six digital inputs
- Two analog inputs
 - 4–20 mA
 - 0–10V
- One analog output
- One digital output
- Two relay outputs
- RS-485 interface

Reliability

- Pretested components: standard
- Computerized testing: standard
- Final test with full load: standard
- Conformal-coated boards
- 50°C rated
- 150% for one minute/10 mm
- 200% for two seconds/20 sec.
- Eaton Electrical Services and Systems: national network of AF drive specialists

M-Max I/O Interface

	Terminal	Signal	Factory Preset	Description
	1	+10V	—	Ref. output voltage Maximum load 10 mA
	2	AI1	Freq. reference ^{P1}	Analog signal in 1 0–+10V Ri = 200k ohms [min.]
	3	GND	—	I/O signal ground
	6	24V	—	24V output for DIIs ±20%, max. load 50 mA
	7	GND	—	I/O signal ground
	8	DI1	Start forward ^{P1}	Digital input 1 0–+30V Ri = 12k ohms min.
	9	DI2	Start reverse ^{P1}	Digital input 2
	10	DI3	Preset speed ^{P1}	Digital input 3
	A	A	FB communication	RS-485 signal A
	B	B	FB communication	RS-485 signal B
AUTOGEN Ref Current	4	AI2	PI actual value ^{P1}	Analog signal in 2 0[4]–20 mA, Ri = 200k ohms
	5	GND	—	I/O signal ground
	13	GND	—	I/O signal ground
	14	DI4	Preset speed B1 ^{P1}	Digital input 4 0–+30V Ri = 12k ohms min.
	15	DI5	Fault reset ^{P1}	Digital input 5 0–+30V Ri = 12k ohms min.
	16	DI6	Disable PI contr. ^{P1}	Digital input 6 0–+30V Ri = 12k ohms min.
Analog OUT	18	A0	Output frequency ^{P1}	Analog output 0[2]–10V, RL = 500 ohms
	20	D0	Active = READY ^{P1}	Digital signal out Open collector, max. load 48V/50 mA
	22	R011	Relay out 1 Active = RUN ^{P1}	Max. switching load: 250 Vac/2A or 250 Vdc/0.4A
	23	R012		
	24	R021	Relay out 2 Active = FAULT ^{P1}	Max. switching load: 250 Vac/2A or 250 Vdc/0.4A
	25	R022		
	26	R023		

Note

^{P1} Parameter-selectable function.